

# **Soar Agents in Government Applications**

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#### **Overview**

- Beginning with TacAir-Soar, Soar Technology has developed a family of intelligent agent systems for various government applications
- This talks describes a sampling of these agents, together with lessons learned from developing them
  - Does not include all of our agent systems, particularly some of those covered by other talks at this workshop



### **TacAir-Soar**

- Yes, it's still around
- Used in SAGIS system for training terminal air controllers
  - Integrated with JSAF
  - Expanding and refining behaviors for close-air support missions
- Soar details
  - Soar 7.0.4
  - About 8000 productions
  - · "Michigan approach" to goal representation
  - "Floating operators" and "persistent elaborations"
- Other innovations
  - Message parsing modules (see later talk)
- Other notes

#### **Helo-Soar**

- Used in Automated Wingman system for Army experimentation
  - Integrated with MÄK Technologies' VR-Forces simulator
  - Providing wingman support roles for helicopter groups in air assault and strike missions
- Used in SAGIS system for training terminal air controllers
  - Integrated with JSAF
  - · Expanding and refining behaviors for close-air support missions
- Soar details
  - Soar 8.6 (with Soar Technology modifications)
  - About 700 productions before close-air-support
  - · "Radical Randy" approach to goal representation
    - · I-supported goal DAG on top state
- Other innovations
  - Some use of TCL code-generation templates
  - Voice interface using ANGST semantic parser
  - · Serious application of "Behavior design patterns"
    - · Iterator, incoming message handler, etc.



#### **IF-Soar**

- Used in SAGIS system for training terminal air controllers
  - Integrated with JSAF
  - Behaviors for Indirect Fire missions as part of coordinated close-air support missions
- Soar details
  - Soar 8.6 (with Soar Technology modifications)
  - About 1400 productions
  - · "New Goal System" approach to goal representation
    - · Variation of "Radical Randy"
    - · O-supported goal DAG on top state
- Other innovations
  - · Significant use of TCL code-generation templates
  - Voice interface using ANGST semantic parser
  - Serious application of "Behavior design patterns"
    - · Iterator, incoming message handler, etc.
  - Introduction of Soar 8 into JSAF
  - Extensive use of UML-like design language for agent design



### Component technologies and reuse

- "Radical Randy" representation of goals
- "New goal system" representation
- TCL code-generation templates
- ANGST semantic parser
- Behavior design patterns
- UML-like design language



## Top-state goal representation

- Allows multiple goals to be arranged in a tree, forest, or DAG
- Allows simultaneous activation of multiple goals
- Operators stay selected for only one decision; no operator subgoaling
- High match costs are possible
- Need knowledge for interleaving operators that attend to multiple parallel goals
- Tradeoffs between "Radical Randy" and "New Goal System"
  - I-support
    - Automatic clean-up of old goals (and their subgoals)
    - · Takes full advantage of Soar's reason maintenance system
  - O-support
    - Sometimes you want goals to persist
    - · Allows reasoning about past achieved and failed goals
    - · Can make debugging easier because goals don't just disappear



## TCL code-generation templates

- "Macros" for common patterns that appear in productions
- Allow representation changes by changing the codegeneration rather than the source code
- Templates can be general or domain-specific
- Allows mixing of templates and "primitive" code sp "explain-agent\*create-subgoal\*achieve-generate-situation-summary [sub-goal-creation <glist> <supergoal>] [is-most-derived-type <supergoal> explain-agent] (<s> ^situation-kb.vista-situation <vs>) (<vs> ^timestamp <time>) --> [create-sub-goal <glist> achieve-generate-situation-summary <supergoal>] (<new-goal> ^vista-situation <vs>) [create-object <new-goal> document-sections class\_Collection <ds> <dstags>]"



## **Expanded template**

```
sp {explain-agent*create-subgoal*achieve-generate-situation-summary
  (state <s> \(^{\superstate}\) nil
             ^situation-kb.vista-situation <vs>
             ^qoals <qoals>)
  (<goals> ^active.goal <supergoal>
            ^all <qlist>)
  (<vs> ^timestamp <time>)
  (<supergoal> ^type-info.most-derived-type explain-agent)
-->
  (<glist> ^goal <new-goal>)
  (<new-goal> ^tags <new-tags>
                ^type-info <type-info-109>
                ^supergoal <supergoal>
                ^vista-situation <vs>
                ^document-sections <ds>)
  (<type-info-109> ^most-derived-type achieve-generate-situation-summary
                    ^all-types <types-110>)
  (<types-110> ^type achieve-generate-situation-summary
                ^type achievement-goal)
  (<ds> ^tags <dstags>
         ^type-info <type-info-113>)
  (<type-info-113> ^most-derived-type |class_Collection|
                    ^all-types.type |class_Collection| +)
```

### **ANGST** semantic parser

- Maps multiple message forms to an architecture-neutral ontological form
- Transmits neutral representation through ATE onto agent input-link

```
<name>Brian</name>
<age>26</age>
<mom-name>Lynn</mom-name>
</content>
<message>

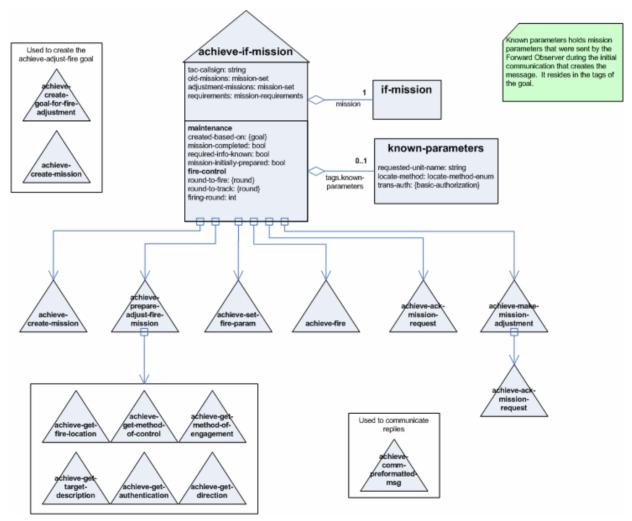
^input-link
   ^message
   ^content
        ^name |Brian|
        ^age 26
        ^mom-name |Lynn|
```

<message>

<content>



# **UML-like design language**



### Gold

- We are still building knowledge-intensive agents
- We are getting better at it
- We have developed new technologies for improving and streamlining the design of agents
- We are starting to see significant reuse across knowledgeintensive agents



### Coal

- Building these agents is still hard to do
- Need to refine and improve technologies and reuse
- Lots of room still for improvement

